

### DESCRIPTION

The MP2144 is a monolithic, step-down, switch-mode converter with internal power MOSFETs. It can achieve up to 2A continuous output current from a 2.5V-to-5.5V input voltage with excellent load and line regulation. The output voltage can be regulated to as low as 0.6V.

The constant-on-time control scheme provides fast transient response and eases loop stabilization. Fault condition protections include cycle-by-cycle current limiting and thermal shutdown.

The MP2144 is available in small TSOT23-8 package and requires only a minimal number of readily available standard external components.

The MP2144 is ideal for a wide range of applications including high-performance DSPs, FPGAs, smartphones, portable instruments, and DVD drivers.

### FEATURES

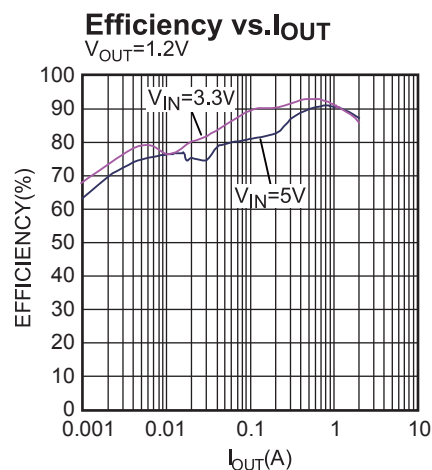
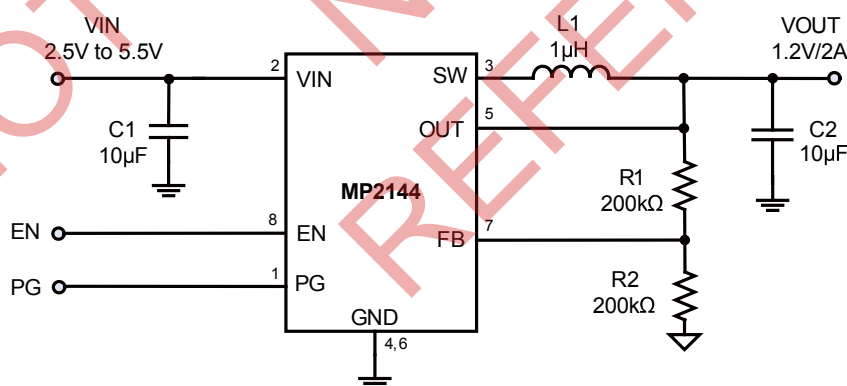
- Wide 2.5V-to-5.5V Operating Input Range
- Output Voltage as Low as 0.6V
- 100% Duty Cycle in Dropout
- Up to 2A Output Current
- Low I<sub>Q</sub>: 40µA
- 90mΩ and 60mΩ Internal Power MOSFET Switches
- Default 1.2MHz Switching Frequency
- EN and Power-Good for Power Sequencing
- Cycle-by-Cycle Over-Current Protection
- Auto Discharge at Power-Off
- Short-Circuit Protect with Hiccup Mode
- Stable with Low-ESR Output Ceramic Capacitors
- Available in a TSOT23-8 Package

### APPLICATIONS

- Low Voltage I/O System Power
- Handheld/Battery-powered Systems
- Wireless/Networking Cards

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### TYPICAL APPLICATION

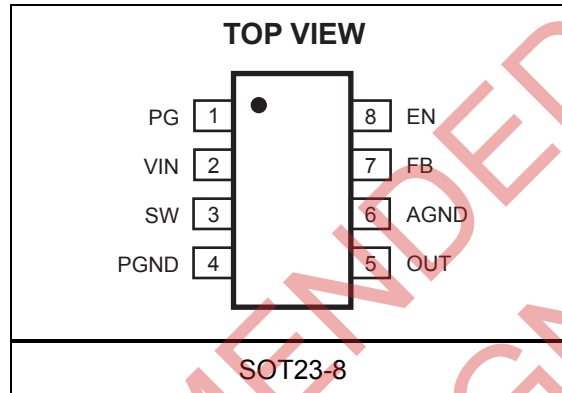


## ORDERING INFORMATION

Part Number*	Package	Top Marking
MP2144GJ	TSOT23-8	ADL

\* For Tape & Reel, add suffix -Z (e.g. MP2144GJ-Z);

## PACKAGE REFERENCE



### ABSOLUTE MAXIMUM RATINGS <sup>(1)</sup>

Supply Voltage V <sub>IN</sub> .....	6V
V <sub>SW</sub> ..... (-3V for < 5ns) to (V <sub>IN</sub> +0.3V)	
All Other Pins.....	-0.3V to +6 V
Junction Temperature.....	150°C
Lead Temperature.....	260°C
Continuous Power Dissipation (T <sub>A</sub> = 25°C) <sup>(2)</sup>	1.25W
Storage Temperature.....	-65°C to +150°C

### Recommended Operating Conditions <sup>(3)</sup>

Supply Voltage V <sub>IN</sub> .....	2.5V to 5.5V
Output Voltage V <sub>OUT</sub> .....	0.6V to V <sub>IN</sub> -0.5V
Operating Junction Temp. (T <sub>J</sub> ).....	-40°C to +125°C

### Thermal Resistance <sup>(4)</sup>

	$\theta_{JA}$	$\theta_{JC}$
TSOT23-8.....	100	55... °C/W

#### Notes:

- Exceeding these ratings may damage the device.
- The maximum allowable power dissipation is a function of the maximum junction temperature T<sub>J</sub> (MAX), the junction-to-ambient thermal resistance  $\theta_{JA}$ , and the ambient temperature T<sub>A</sub>. The maximum allowable continuous power dissipation at any ambient temperature is calculated by P<sub>D</sub> (MAX) = (T<sub>J</sub> (MAX)-T<sub>A</sub>)/ $\theta_{JA}$ . Exceeding the maximum allowable power dissipation will cause excessive die temperature, and the regulator will go into thermal shutdown. Internal thermal shutdown circuitry protects the device from permanent damage.
- The device is not guaranteed to function outside of its operating conditions.
- Measured on JESD51-7, 4-layer PCB.

# **ELECTRICAL CHARACTERISTICS <sup>(5)</sup>**

**V<sub>IN</sub> = 5V, T<sub>A</sub> = 25°C, unless otherwise noted.**

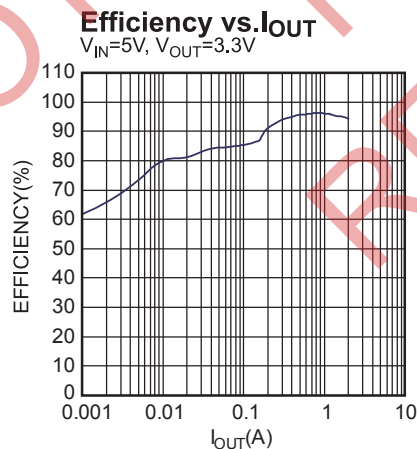
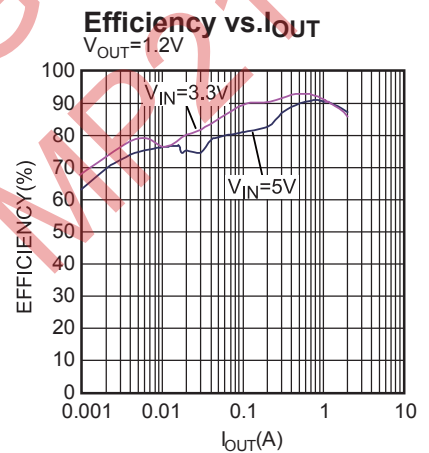
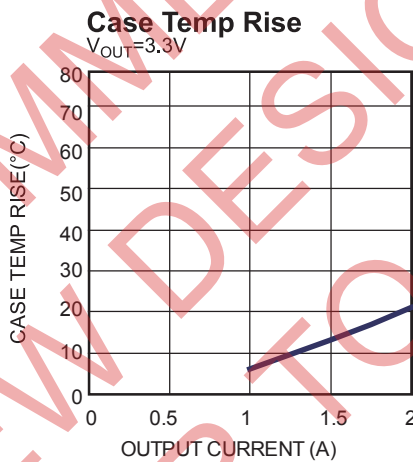
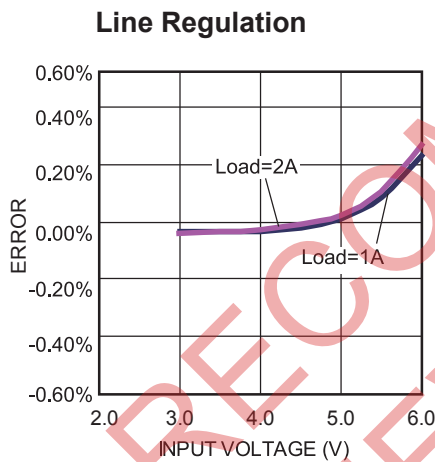
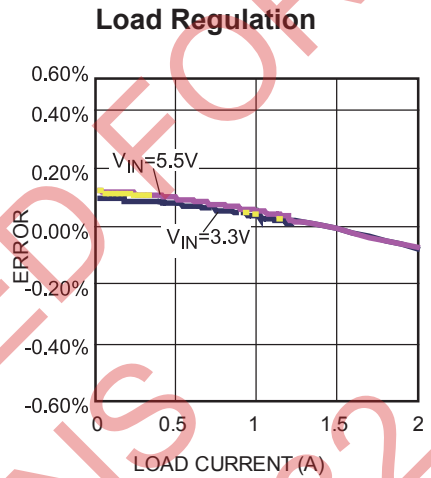
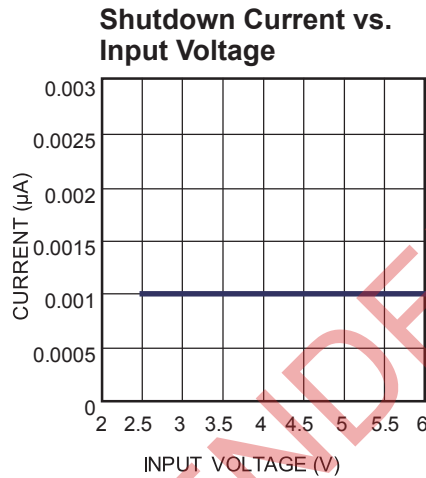
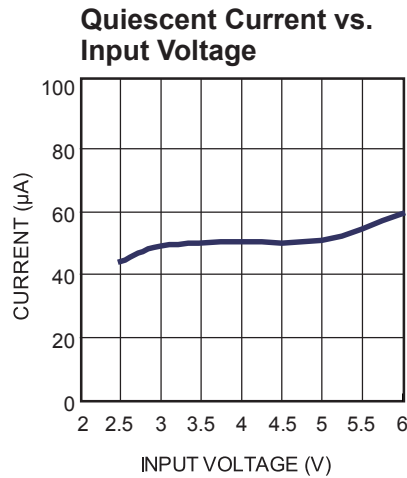
Parameter	Symbol	Condition	Min	Typ	Max	Units
Feedback Voltage	V <sub>FB</sub>	2.5V ≤ V <sub>IN</sub> ≤ 5.5V	-1.5%	0.600	+1.5%	V/%
		T <sub>A</sub> = -40°C to +85°C	-2%		+2%	
Feedback Current	I <sub>FB</sub>	V <sub>FB</sub> = 0.63V		10		nA
PFET Switch ON Resistance	R <sub>DS(on)_P</sub>			90		mΩ
NFET Switch ON Resistance	R <sub>DS(on)_N</sub>			60		mΩ
Switch Leakage		V <sub>EN</sub> = 0V, V <sub>IN</sub> = 5V V <sub>SW</sub> = 0V and 5V		0.1	2	μA
PFET Current Limit			3.3	3.8		A
NFET Switch Sinking Current	I <sub>NSW</sub>	V <sub>OUT</sub> = 1.2V, V <sub>FB</sub> = 0.7V		100		μA
ON Time	t <sub>ON</sub>	V <sub>IN</sub> = 5V, V <sub>OUT</sub> = 1.2V		200		nS
		V <sub>IN</sub> = 3.6V, V <sub>OUT</sub> = 1.2V		277		
Switching frequency	f <sub>s</sub>	V <sub>IN</sub> = 5V, V <sub>OUT</sub> = 1.2V, I <sub>OUT</sub> = 1A	-20%	1200	+20%	kHz
		T <sub>A</sub> = -40°C to +85°C	-25%	1200	+25%	
Minimum OFF Time	t <sub>MIN-OFF</sub>			50		ns
Soft-Start Time	t <sub>SS-ON</sub>			1.3		ms
Soft-Stop Time	t <sub>SS-OFF</sub>			1		ms
Power-Good Upper Trip Threshold	PG <sub>H</sub>	FB voltage with respect to the regulation		+10%		%
Power-Good Lower Trip Threshold	PG <sub>L</sub>			-10%		%
Power-Good Delay	PG <sub>D</sub>			110		μs
Power-Good Sink Current Capability	V <sub>PG-L</sub>	Sink 1mA			0.4	V
Power Good Logic High Voltage	V <sub>PG-H</sub>	V <sub>IN</sub> = 5V, V <sub>FB</sub> = 0.6V	4.9			V
Power Good Internal Pull-Up Resistor	R <sub>PG</sub>			500		kΩ
Under-Voltage Lockout Threshold Rising			2.0	2.2	2.4	V
Under-Voltage Lockout Threshold Hysteresis				150		mV
EN Input Logic Low Voltage					0.4	V
EN Input Logic High Voltage			1.2			V
EN Input Current		V <sub>EN</sub> = 2V		2		μA
		V <sub>EN</sub> = 0V		0.1		μA
Supply Current (Shutdown)		V <sub>EN</sub> = 0V		0.1		μA
Supply Current (Quiescent)		V <sub>EN</sub> = 2V, V <sub>FB</sub> = 0.63V, V <sub>IN</sub> = 3.6V		40		μA
Thermal Shutdown				150		°C
Thermal Hysteresis				30		°C

## **Notes:**

5) Guaranteed by design.

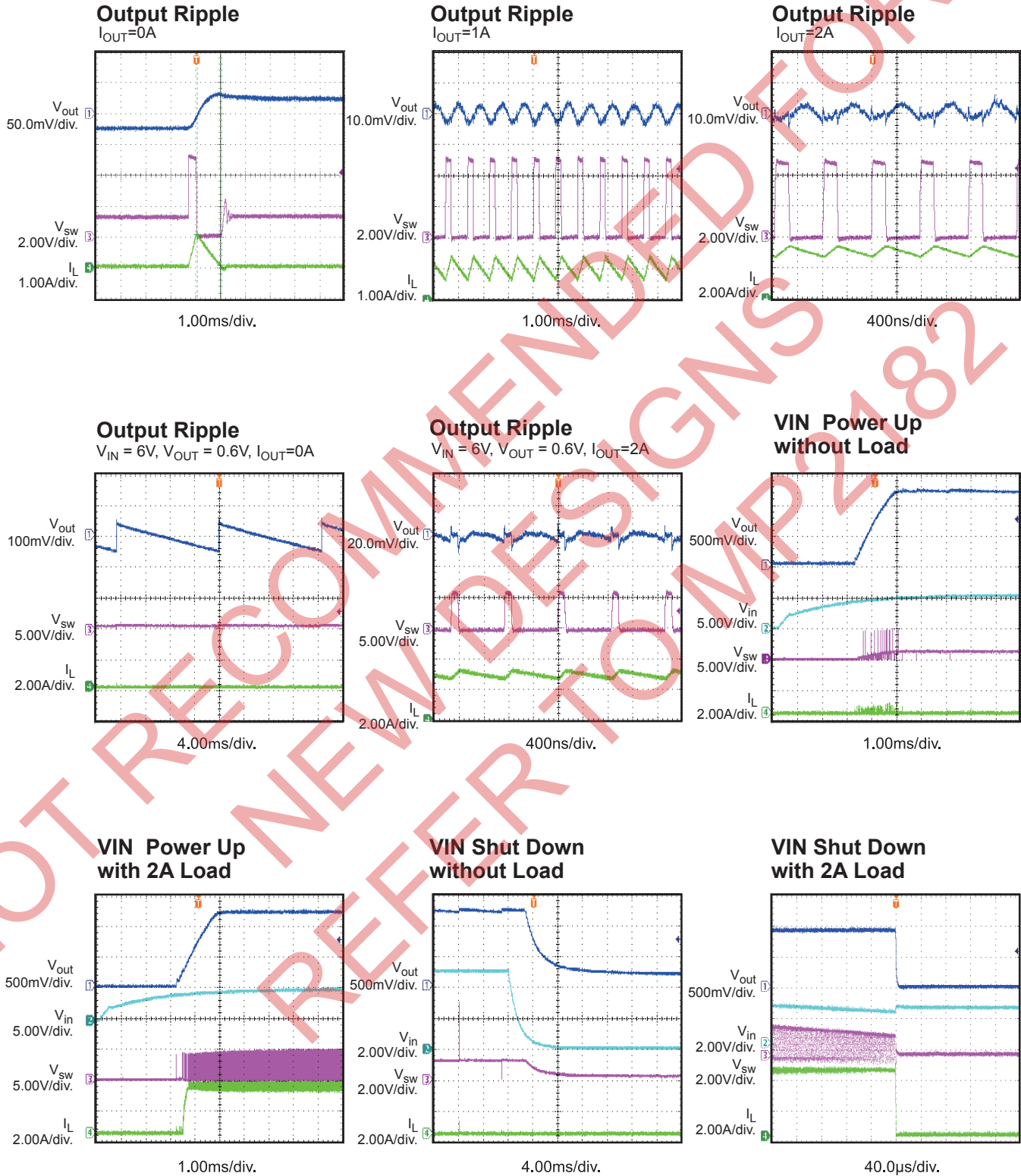
## TYPICAL PERFORMANCE CHARACTERISTICS

$V_{IN} = 5V$ ,  $V_{OUT} = 1.2V$ ,  $L = 1.0\mu H$ ,  $C_{OUT} = 22\mu F$ ,  $T_A = 25^\circ C$ , unless otherwise noted.



## TYPICAL PERFORMANCE CHARACTERISTICS (continued)

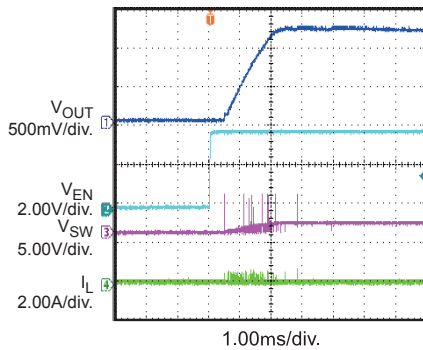
$V_{IN} = 5V$ ,  $V_{OUT} = 1.2V$ ,  $L = 1.0\mu H$ ,  $C_{OUT} = 22\mu F$ ,  $T_A = 25^\circ C$ , unless otherwise noted



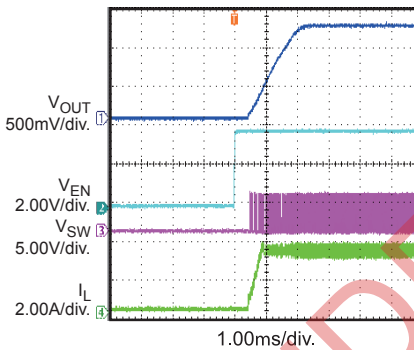
# **.TYPICAL PERFORMANCE CHARACTERISTICS (continued)**

$V_{IN} = 5V$ ,  $V_{OUT} = 1.2V$ ,  $L = 1.0\mu H$ ,  $C_{OUT} = 22\mu F$ ,  $T_A = 25^\circ C$ , unless otherwise noted.

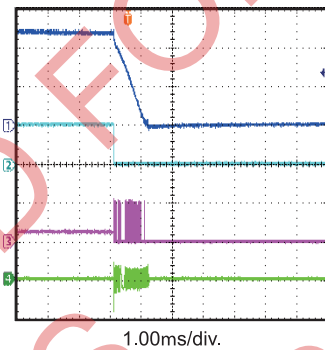
**EN Start Up without Load**



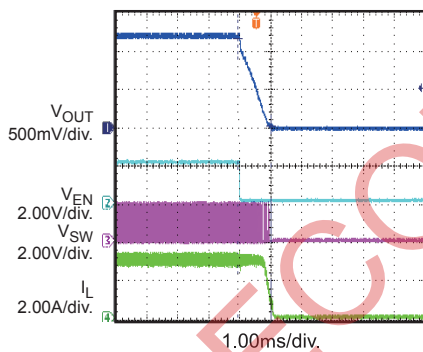
**EN Start Up with 2A Load**



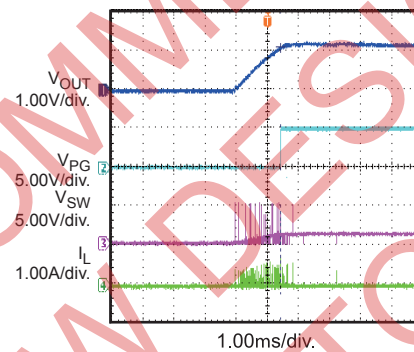
**EN Shut Down without Load**



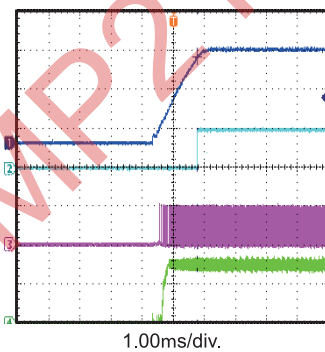
**EN Shut Down with 2A Load**



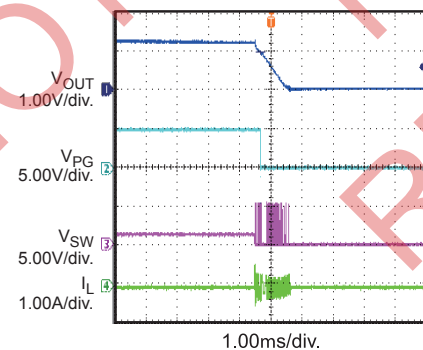
**Power Good On without Load**



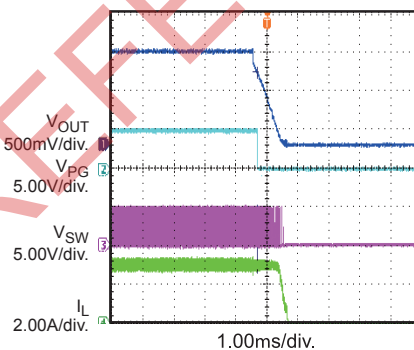
**Power Good On with 2A Load**



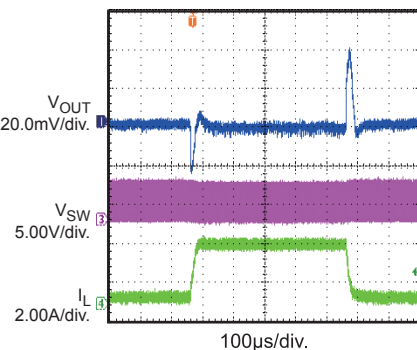
**Power Good Off without Load**



**Power Good Off with 2A Load**

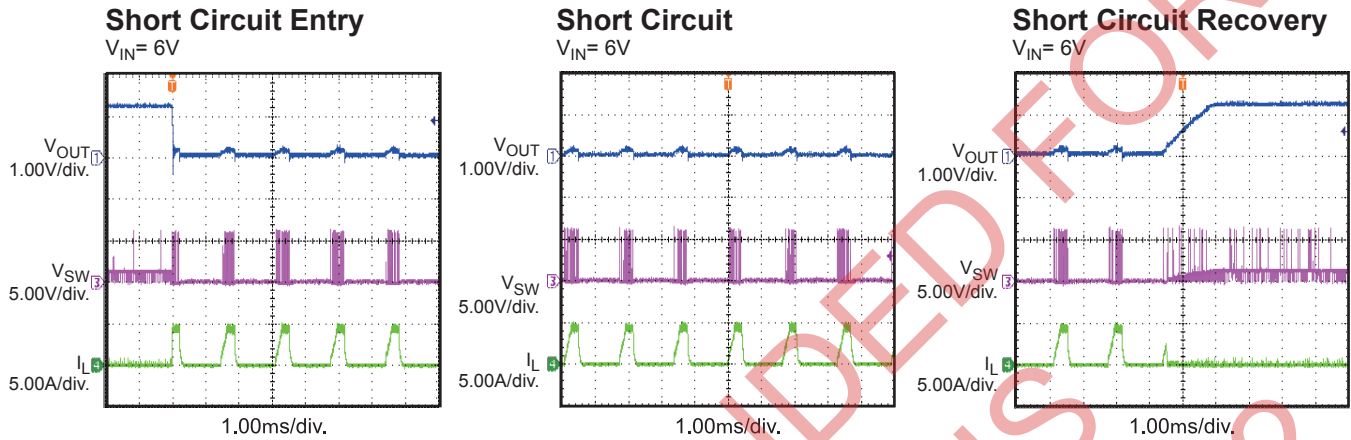


**Load Transient Response**



## TYPICAL PERFORMANCE CHARACTERISTICS *(continued)*

$V_{IN} = 5V$ ,  $V_{OUT} = 1.2V$ ,  $L = 1.0\mu H$ ,  $C_{OUT} = 22\mu F$ ,  $T_A = 25^\circ C$ , unless otherwise noted.



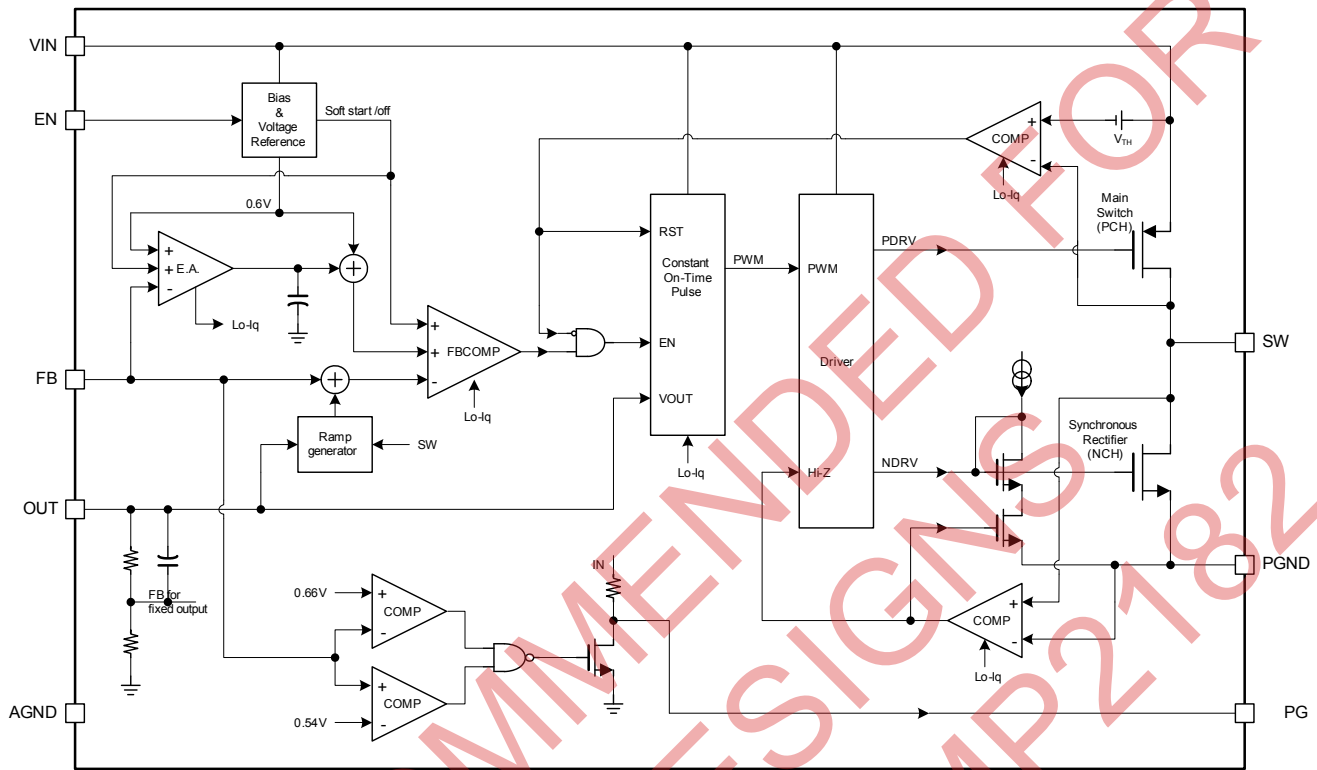


## PIN FUNCTION

TSOT23 Pin #	Name	Description
1	PG	Power Good Indicator. The output of this pin is an open drain with an internal pull up resistor to IN. PG is pulled up to VIN when the FB voltage is within 10% of the regulation level. If the FB voltage is out of that regulation range, it is LOW.
2	VIN	Supply Voltage. The MP2144 operates from a +2.5V-to-+5.5V unregulated input. C1 prevents large voltage spikes from appearing at the input.
3	SW	Switch Output
4	PGND	Power Ground
5	OUT	Input Sense. For output voltage sense.
6	AGND	Analog Ground. Internal control circuit reference.
7	FB	Feedback. Connect an external resistor divider from the output to GND to set the output voltage.
8	EN	On/Off Control



## FUNCTIONAL BLOCK DIAGRAM



**Figure 1: Functional Block Diagram**

## OPERATION

The MP2144 uses constant on-time control with input voltage feed-forward to stabilize the switching frequency over its full input range. At light load, the MP2144 employs proprietary control over the low-side MOSFET (LS-FET) and inductor current to eliminate ringing on switching node and improve efficiency.

### Constant-On-Time Control

When compared to fixed-frequency PWM control, constant-on-time control offers advantages including simpler control loop and faster transient response. By using input voltage feed-forward, the MP2144 maintains a nearly constant switching frequency across the entire input and output voltage range. The on-time of the switching pulse can be estimated as:

$$t_{ON} = \frac{V_{OUT}}{V_{IN}} \cdot 0.833\mu s$$

To prevent inductor current runaway during the load transient, the MP2144 has a fixed minimum off time of 50ns. However, this minimum off time limit does not affect the operation of the MP2144 in steady state in any way.

### Light-Load Operation

Under light-load conditions, the MP2144 uses a proprietary control scheme to save power and improve efficiency: it gradually ramps down the LS-FET current to its minimum instead of turning off the LS-FET immediately when the inductor current starts to reverse. The gradual current drop avoids ringing at the switching node that always occurs in discontinuous conduction mode (DCM) operation.

### Enable

When the input voltage exceeds the under-voltage lockout (UVLO) threshold—typically 2.2V—the MP2144 can be enabled by pulling the EN pin higher than 1.2V. Leaving EN pin

floating or grounded will disable the MP2144. There is an internal 1MΩ resistor from the EN pin to ground.

### Soft-Start/Stop

MP2144 has a built-in soft-start that ramps up the output voltage at a constant slew rate that avoids overshooting at startup. The soft-start time is typically about 1ms. When disabled, the MP2144 ramps down the internal reference voltage to allow the load to linearly discharge the output.

### Power GOOD Indicator

MP2144 has an open drain with a 500kΩ pull-up resistor pin for power good (PG) indication. When the FB pin is within ±10% of the regulatory voltage (0.6V), the PG pin is pulled up to VIN by the internal resistor. If the FB pin voltage is outside the ±10% window, the PG pin is pulled to ground by an internal MOSFET. The MOSFET has a maximum R<sub>dson</sub> of less than 100Ω.

### Current limit

The MP2144 has a 3.3A minimum current limit for the high side switch (HS-FET). When the HS-FET hits its current limit, MP2144 enters hiccup mode until the current drops to prevent the inductor current from rising and possibly damaging the components.

### Short Circuit and Recovery

The MP2144 also enters short-circuit protection (SCP) mode when it hits the current limit, and tries to recover from the short circuit by entering hiccup mode. In SCP, the MP2144 disables the output power stage, discharges a soft-start capacitor, and then enacts a soft-start procedure. If the short-circuit condition still holds after soft-start ends, the MP2144 repeats this operation until the short circuit ceases and output rises back to regulation level.

## APPLICATION INFORMATION

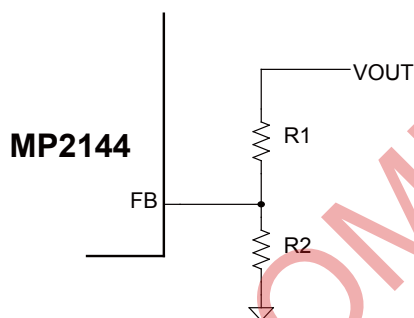
### COMPONENT SELECTION

#### Setting the Output Voltage

The external resistor divider sets the output voltage (see the Typical Application schematic on page 1). The design of the feedback resistor R1 must account for both stability and dynamic response, and thus can not be too large or too small. Choose an R1 value between 120kΩ and 200kΩ. R2 is then given by:

$$R2 = \frac{R1}{\frac{V_{out}}{0.6} - 1}$$

The feedback circuit is shown in Figure 2.



**Figure 2: Feedback Network**

Table 1 lists the recommended resistors values for common output voltages.

**Table 1: Resistor Values for Common Output Voltages**

V <sub>OUT</sub> (V)	R1 (kΩ)	R2 (kΩ)
1.0	200(1%)	300(1%)
1.2	200(1%)	200(1%)
1.8	200(1%)	100(1%)
2.5	200(1%)	63.2(1%)
3.3	200(1%)	44.2(1%)

#### Selecting the Inductor

A 0.82μH to 4.7μH inductor is recommended for most applications. For the best efficiency, choose an inductor with a DC resistance less than 15mΩ. For most designs, the inductance value can be derived from the following equation.

$$L_1 = \frac{V_{OUT} \times (V_{IN} - V_{OUT})}{V_{IN} \times \Delta I_L \times f_{OSC}}$$

Where ΔI<sub>L</sub> is the inductor ripple current.

Choose an inductor current to be approximately 30% of the maximum load current. The maximum inductor peak current is:

$$I_{L(MAX)} = I_{LOAD} + \frac{\Delta I_L}{2}$$

#### Selecting the Input Capacitor

The input current to the step-down converter is discontinuous, and requires a capacitor to supply the AC current to the step-down converter while maintaining the DC input voltage. Use low-ESR capacitors for the best performance. Ceramic capacitors with X5R or X7R dielectrics are highly recommended because of their low ESR values and small temperature coefficients. For most applications, a 10μF capacitor is sufficient. For higher output voltage, 47μF may be needed to increase system stability.

Since the input capacitor absorbs the input switching current it requires an adequate ripple current rating. The RMS current in the input capacitor can be estimated by:

$$I_{C1} = I_{LOAD} \times \sqrt{\frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)}$$

The worse case condition occurs at V<sub>IN</sub> = 2V<sub>OUT</sub>, where:

$$I_{C1} = \frac{I_{LOAD}}{2}$$

For simplification, choose an input capacitor whose RMS current rating is greater than half of the maximum load current.

The input capacitor can be electrolytic, tantalum, or ceramic. When using electrolytic or tantalum capacitors, use a small, high-quality, ceramic capacitor (0.1μF) placed as close to the IC as possible. When using ceramic capacitors, make sure that they have enough capacitance to prevent excessive voltage ripple at the input.

The input voltage ripple caused by capacitance can be estimated by:

$$\Delta V_{IN} = \frac{I_{LOAD}}{f_s \times C1} \times \frac{V_{OUT}}{V_{IN}} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

### Selecting the Output Capacitor

The output capacitor (C2) maintains the output DC voltage. Use Ceramic capacitors. Low ESR capacitors keep the output voltage ripple low. The output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L_1} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times \left(R_{ESR} + \frac{1}{8 \times f_s \times C2}\right)$$

Where L<sub>1</sub> is the inductor value and R<sub>ESR</sub> is the equivalent series resistance (ESR) value of the output capacitor.

Using ceramic capacitors, the impedance at the switching frequency is dominated by the capacitance. The output voltage ripple is mainly caused by the capacitance. For simplification, the output voltage ripple can be estimated by:

$$\Delta V_{OUT} = \frac{V_{OUT}}{8 \times f_s^2 \times L_1 \times C2} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right)$$

For tantalum or electrolytic capacitors, the ESR dominates the impedance at the switching frequency. For simplification, the output ripple can be approximated as:

$$\Delta V_{OUT} = \frac{V_{OUT}}{f_s \times L_1} \times \left(1 - \frac{V_{OUT}}{V_{IN}}\right) \times R_{ESR}$$

The characteristics of the output capacitor also affect the stability of the regulation system.

### PCB Layout Recommendation

Proper layout of the switching power supplies is very important, and sometimes critical for proper function. For the high-frequency switching converter, poor layout design can result in poor line or load regulation and stability issues.

The high current paths (GND, IN, and SW) should be placed very close to the device using short, direct, and wide traces. The input capacitor needs to be as close as possible to the IN and GND pins. The external feedback resistors should be placed next to the FB pin. Keep the switching node SW short and away from the feedback network.

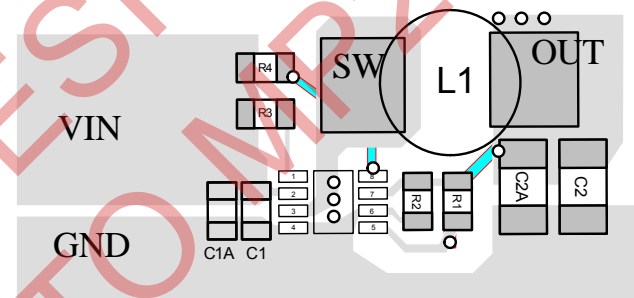
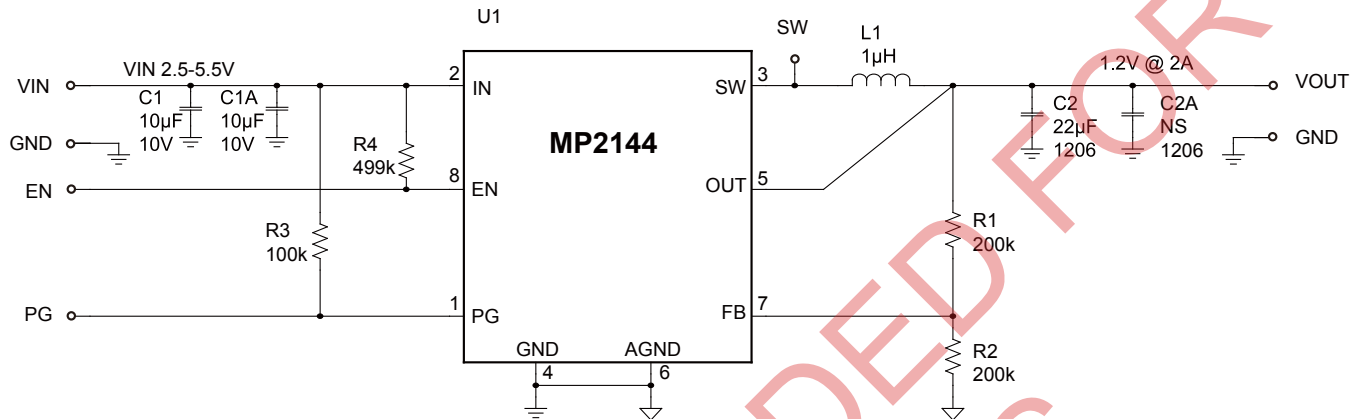


Figure 3: Layout Recommendation

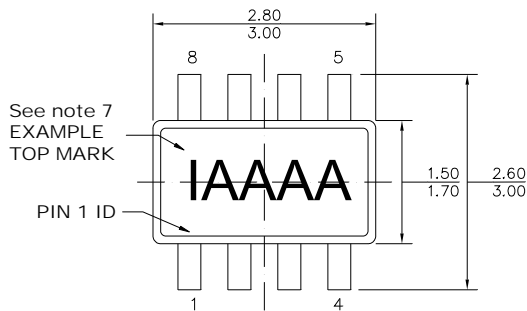
## TYPICAL APPLICATION CIRCUIT



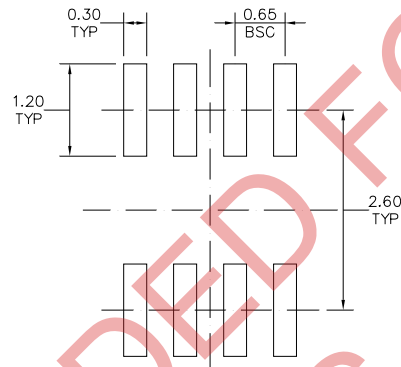
### Figure 4: MP2144 Typical Application Circuit

## PACKAGE INFORMATION

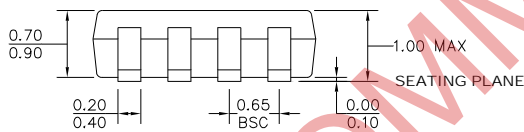
### TSOT23-8



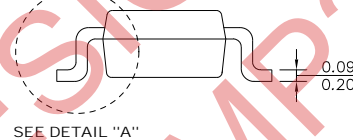
TOP VIEW



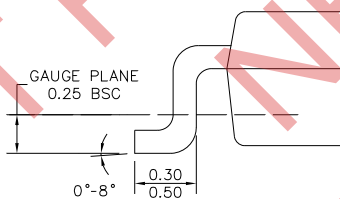
RECOMMENDED LAND PATTERN



FRONT VIEW



SIDE VIEW



DETAIL "A"

#### NOTE:

- 1) ALL DIMENSIONS ARE IN MILLIMETERS.
- 2) PACKAGE LENGTH DOES NOT INCLUDE MOLD FLASH, PROTRUSION OR GATE BURR.
- 3) PACKAGE WIDTH DOES NOT INCLUDE INTERLEAD FLASH OR PROTRUSION.
- 4) LEAD COPLANARITY (BOTTOM OF LEADS AFTER FORMING) SHALL BE 0.10 MILLIMETERS MAX.
- 5) JEDEC REFERENCE IS MO-193, VARIATION BA.
- 6) DRAWING IS NOT TO SCALE.
- 7) PIN 1 IS LOWER LEFT PIN WHEN READING TOP MARK FROM LEFT TO RIGHT, (SEE EXAMPLE TOP MARK)

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